

Cost-Sensitive Precomputation of Real-Time-Aware Reconfiguration Strategies based on Stochastic Priced Timed Games

(published in Journal on Software and Systems Modeling, 2024)

Hendrik Göttmann, Birte Caesar, Lasse Beers, <u>Malte</u> Lochau, Andy Schürr, Alexander Fay

SE 25, Karlsruhe



www.uni-siegen.de

Example: Robot Support System for Aircraft Assemblies



[Banku, CC BY-SA 4.0 <https://creativecommons.org/licenses/by-sa/4.0>, via Wikimedia Commons]

Workstation **Human Workers** Left with Service 000000886088 000 Requests Workstation Inside 000 000 888888000000) Workstation Service Right Station Mobile Robots with Mountable Tools: Positioning Riveting . (©©)

[Brunete et al.: Current trends in reconfigurable modular robots design (2017) https://doi.org/10.1177/1729881417710457]



Challenges & Approach

Functional requirements:

- *Reactive/proactive decision procedure to assign robots to service requests.*
- Continuous reconfiguration of robots to adapt to changing contexts at run-time.

Non-functional optimization goals:

- Maximize productivity (maximize utilization of robots / minimize waiting time of workers),
- Minimize costs (minimize number of robots / minimize overall energy consumption)



- > Entirely deciding assignments of robots to tasks **before** run-time is infeasible due to many sources of **uncertainty**.
- Entirely deciding assignments of robots to tasks during run-time is also infeasible due to the high computational complexity of the underlying optimization problem.
- > Our approach: **Precompute** as many decisions as possible off-line and make final decisions on-line.

[Filieri et al.: Run-time efficient probabilistic model checking (2011). https://doi.org/10.1145/1985793.1985840]





Context-Feature Models



Contextual System Configuration Constraints

[Hartmann, Trew, T.: Using Feature Diagrams with Context Variability to Model Multiple Product Lines for Software Supply Chains (2008). https://doi.org/10.1109/SPLC.2008.15]





Reconfiguration Constraints

- Logical Constraint: Forbidden Reconfiguration
- Real-time Constraint: Duration of Robot Movement
- Real-time Constraint: Duration of Tool Change
- Stochastic Constraint: Probability of Task Requests
- Cost Constraint: Energy Consumption of Tool Change
- Cost Constraint: Penalty for Unfinished Task

```
[Left → Right] false
[Left → ServiceStation] setup(30)
[ServiceStation ∧ PositioningTool →
ServiceStation ∧ RivetingTool] setup(50)
[¬Task → Task] normal(30,5)
[PositioningTool → RivetingTool] cost(1)
[Task] cost(2)
```





Reconfiguration Model







Reconfiguration Game



Stochastic Priced Timed Game Automaton

Stochastic Context Changes

Precomputing Reconfiguration Strategies



- Winning Strategy Synthesis: Precomputed reconfiguration decisions satisfy critical context requirements for all predicted context changes.
- Optimized Strategy Synthesis: Precomputed reconfiguration decisions additionally try to reach optimality w.r.t. NFP goals.
- UPPAAL Stratego applies statistical model-checking to approximate correct/optimal solutions.

[David et al.: On time with minimal expected costs (2014). https://doi.org/10.1007/978-3-319-11936-6_10]



Outlook

- Develop efficient run-time data structures to deploy reconfiguration strategies on target systems with limited resources.
- Conduct further real-word case studies from communication networks and automation systems.
- Identify needs for extending the reconfiguration constraint modeling language.
- Investigate further counter-measures to cope with the inherent computational complexity of strategy synthesis.

- For more details, have a look into our paper: <u>https://doi.org/10.1007/s10270-024-01195-9</u>
- Contact: <u>malte.Lochau@uni-siegen.de</u>

